

# Dance Floor Emergency

**COPPER** **KNOB**  
BY STEPSHEETS

Count: 32

Wand: 4

Ebene: Improver

Choreograf/in: Ryan Hunt (UK) - February 2025

Musik: Dance Floor Emergency - Chloe Jane



**Intro: 16 counts (after 8 seconds)**

## Rocking Chair, Jazz Box 1/4 Cross

- 1-2 Rock R forward (1), Recover on L (2)
- 3-4 Rock R back (3), Recover on L (4)
- 5-6 Cross R over L (5), Make 1/4 R stepping back on L (6) [3:00]
- 7-8 Step R to R (7), Cross L over R (8)

## Side, HOLD, & Side Touch, Rolling Vine

- 1-2 Step R to R (1), HOLD (2)
- &3-4 Quickly close L next to R (&), Step R to R (3), Touch L next to R (4)
- 5-6 Make 1/4 L stepping L forward (5) [12:00], Make 1/2 L stepping R back (6) [6:00]
- 7-8 Make 1/4 L stepping L to L (7) [3:00], Touch R next to L (8) \*Restart here on Walls 3 & 9

**Non-turning option: replace rolling vine with regular grapevine: side, behind, side, touch.**

## Dorothy Steps x2, Rock Forward, Recover, 1/4 Side, Point

- 1-2& Step R to R diagonal (1), Lock L behind R (2), Step onto R (&)
- 3-4& Step L to L diagonal (3), Lock R behind L (4), Step onto L (&)
- 5-6 Rock R forward (5), Recover on L (6)
- 7-8 Make 1/4 R stepping R to R side (7) [6:00], Point L to L side (8)

## 1/4 Forward, 1/2 Back, Coaster Step, Heel Struts w/ Shoulder Touches & Robot Arms

- 1-2 Make 1/4 L stepping L forward (1) [3:00], Make 1/2 L stepping R back (2) [9:00]
- 3&4 Step L back (3), Close R next to L (&), Step L forward (4)
- 5-6 Dig R heel forward (5), Drop R toes (6)

**Arms: Cross arms over chest touching R hand to L shoulder & L hand to R shoulder (5), Touch hands to respective shoulders i.e. R hand to R shoulder & L hand to L shoulder (6)**

- 7-8 Dig L heel forward (7), Drop L toes (8)

**Arms: Raise R hand forward with palm facing left as left hand is down by left side (7), Switch L hand forward with palm facing right as right hand drops down by right side (8)**

**Restarts: After 16 counts on Walls 3 and 9 (both facing 9:00)**

**Ending: Drop head and look to the floor on count 32 of Wall 12 (facing 12:00), holding the robot pose with the L hand forward!**